

Submittal Data Information Advantage 12 Variable Speed Drive

301-1891

EFFECTIVE: APRIL 26	5, 2016			SUPERSEDES:	JANUARY 19, 2016
JOB			ENGINEER		
CONTRACTOR		RE	EP		
ITEM NO.	MODEL NO.	HP/KW.	SUPPLY VOLTAGE	WEIGHT	
	OPTION	OP*	TION	OP'	TION

SELECTION GUIDE:

	Single Phase							
HP	KW	Supply Voltage	Amps	Model Number	Weight (Lbs)	Weight (KG)		
0.5	0.37	100-120 V 50/60 HZ	2.4	ATV12H037F1M	1.80	0.8		
0.5	0.37	200-240 V 50/60 HZ	2.4	ATV12H037M2M	1.80	0.8		
0.75	0.56	200-240 V 50/60 HZ	3.5	ATV12H055M2	1.80	0.8		
1	0.75	100-120 V 50/60 HZ	4.2	ATV12H075F1M	2.87	1.3		
1	0.75	200-240 V 50/60 HZ	4.2	ATV12H075M2M	1.76	0.8		
2	1.5	200-240 V 50/60 HZ	7.5	ATV12HU15M2M	3.09	1.4		
3	2.2	200-240 V 50/60 HZ	10.0	ATV12HU22M2M	3.09	1.4		

	Three Phase							
HP	KW	Supply Voltage	Amps	Model Number	Weight (Lbs)	Weight (KG)		
0.5	0.37	200-240 V 50/60 HZ	2.4	ATV12H037M3M	1.80	0.8		
1	0.75	200-240 V 50/60 HZ	4.2	ATV12H075M3M	1.76	0.8		
2	1.5	200-240 V 50/60 HZ	7.5	ATV12HU15M3M	2.65	1.2		
3	2.2	200-240 V 50/60 HZ	10.0	ATV12HU22M3M	2.65	1.2		
5	4.0	200-240 V 50/60 HZ	16.7	ATV12HU40M3M	4.41	2.0		





In order to provide the most efficient pump solution to our customers, Taco is now working with Schneider Electric.

This collaboration brings together Taco's pump technology with Schneider Electric Variable Frequency Drives and the drive packaging of Square D enclosures to offer the best overall pumping solution for our customers.



CHARACTERISTICS:

Environmental ch	aracteristics		
Conformity to standards	-		ATV 12 drives have been developed to conform to the strictest international standards and the recommendations relating to electrical industrial control equipment (IEC,EN), in particular: IEC/EN 61800-5-1 (low voltage), IEC/EN 61800-3 (conducted and radiated EMC immunity and emissions).
EMC immunity	,		IEC/EN 61800-3, Environments 1 and 2 (EMC requirements and specific test methods) IEC/EN 61000-4-2 level 3 (electrostatic discharge immunity test) IEC/EN 61000-4-3 level 3 (radiated, radio-frequency, electromagnetic field immunity test) IEC/EN 61000-4-4 level 4 (electrical fast transient/burst immunity test) IEC/EN 61000-4-5 level 3 (surge immunity test) IEC/EN 61000-4-6 level 3 (immunity to conducted disturbances, induced by radio-frequency fields) IEC/EN 61000-4-11 (voltage dips, short interruptions and voltage variations immunity tests)
Conducted an radiated EMC emissions for drives	d ATV 12 ◆◆◆◆ F1 ATV 12H018M3 ATV 12 ● 037M3 ● U22M3		With additional EMC filter: ■ IEC/EN 61800-3, Environment 1 (public network) in restricted distribution: □ Category C1, at 2,4,8,12 and 16 kHz for a shielded motor cable length ≤5 m □ Category C2, from 2 to 16 kHz for a shielded motor cable length ≤ 20 m ■ IEC/EN 61800-3, Environment 2 (industrial network): □ Category C3, from 2 to 16 kHz for a shielded motor cable length ≤ 20 m
	ATV 12 ●●●● M2		 ■ IEC/EN 61800-3, Environment 1 (public network) in restricted distribution: □ Category C1, at 2, 4, 8, 12 and 16 kHz for a shielded motor cable length ≤ 5 m □ Category C2: ATV 12H018M2 ● 075M2, from 2 to 12 kHz for a shielded motor cable length ≤ 5 m and at 2, 4, 16 kHz for a shielded motor cable length ≤ 10 m □ Category C2: ATV 12HU15M2HU22M2, from 4 to 16 kHz for a shielded motor cable length ≤ 5 m and at 2, 4, 8, 12 and 16 kHz for a shielded motor cable length ≤ 10 m
			With additional EMC filter: ■ IEC/EN 61800-3, Environment 1 (public network) in restricted distribution: □ Category C1, at 2, 4,8,12 and 16 kHz for a shielded motor cable length ≤ 20 m □ Category C2, from 2 to 16 kHz for a shielded motor cable length ≤ 50 m ■ IEC/EN 61800-3, Environment 2 (industrial network): □ Category C3, from 2 to 16 kHz for a shielded motor cable length ≤ 50 m
C€ marking			The drives are marked (according to the European low voltage (2006/95/EC) and EMC (2004/108/EC) directives
Product certifications			UL, CSA, NOM, GOST and C-Tick
Degree of protection			IP 20
Vibration resistance	Drive not mounted on rail		According to IEC/EN 60068-2-6: 1.5 mm peak from 3 to 13 Hz 1 gn from 13 to 200 Hz
Shock resistance			15 gn for 11 ms according to IEC/EN 60068-2-27
Maximum ambient pollution Definition of insulation			Degree 2 according to IEC/EN 61800-5-1
Environmental conditions Use			IEC 60721-3-3 classes 3C3 and 3S2
Relative humidity		%	595 non condensing, no dripping water, according to IEC600 68-2-3
Ambient air Operation temperature around the device	ATV 12H018F1,H037F1 ATV 12H018M2H075M2 ATV 12H018M3H075M3 ATV 12P ●●●●●	°C	- 10+40 without derating Up to + 60, with the protective blanking cover removed and current derating of 2.2% per additional degree
	ATV 12H075F1 ATV 12HU15M2, HU22M2 ATV 12HU15M3HU40M3	°C	- 10…+50 without derating Up to + 60, with the protective blanking cover removed and current derating of 2.2% per additional degree
Storage	ATV 12 ●●●●●	°C	-25+70
Maximum operating altitude	<u>ATV</u> 12 ●●●●●	m	1000 without derating
	ATV 12 ● ● ● F1 ATV 12 ● ● ● M2	m	Up to 2000 for single-phase networks and corner grounded distribution networks, with current derating of 1% per additional 100 m
	ATV 12 ● ● ● M3	m	Up to 3000 meters for three-phase networks, with current derating of 1% per additional 100 m
Operating position Maximum permanent angle in relation to the normal vertical mounting position			10°

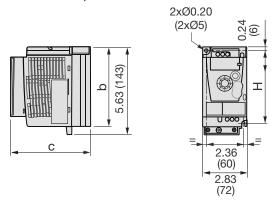
Drive characteristic	S					
Output frequency range		Hz	0.5400			
Configurable switching frequency		kHz	Nominal switching frequency: 4 kHz without derating in continuous operation Adjustable during operation from 2 to 16 kHz Above 4 kHz in continuous operation, apply derating to the nominal drive current of: 10% for 8 kHz 20% for 12 kHz 30% for 16 kHz Above 4 kHz, the drive will reduce the switching frequency automatically in the event of excessive temperature rise.			
Speed range			120			
Transient overtorque			150170% of the nominal torque depend	ling on the drive rating and the type of motor		
Braking torque			■ Up to 70% of the nominal torque witho			
Maximum transient current			150% of the nominal drive current for 60 se	econds		
Motor control profiles			■ Standard profile (voltage/frequency ratio) ■ Performance profile (sensorless flux vector control) ■ Pump/fan profile (Kn² quadratic ratio)			
Electrical power cha	nracteristics					
Power supply	Voltage	V	100 - 15% to 120 + 10% single-phase for ATV 12●●● F1 200 - 15% to 240 + 10% single-phase for ATV 12●●● M2 200 - 15% to 240 + 10% three-phase for ATV 12●●● M3			
	Frequency	Hz	5060±5%			
	lsc (short-circuit current)	А	<1000 (Isc at the connection point) for sing ≤5000 (Isc at the connection point) for three	gle-phase power supply ee-phase power supply		
Drive supply and output voltage	rs		Drive supply voltage	Drive output voltage for motor		
	ATV 12 pppp F1	V	100120 single-phase	200240 three-phase		
	ATV 12 pppp M2	V	200240 single-phase	_		
	ATV 12 pppp M3	V	200240 three-phase			
Maximum length of motor cable (including tap links)	Shielded cable	m	50			
cable (including tap inits)	Unshielded cable	m	100			
Drive noise level	ATV 12H018F1,H037F1 ATV 12H018M2H075M2 ATV 12H018M3H075M3 ATV 12P ppppp	dBA	0			
	ATV 12H075F1 ATV 12HU15M2, HU22M2	dBA	45			
	ATV 12HU15M3HU40M3	dBA	50			
Electrical isolation			Electrical isolation between power and cor	ntrol (inputs, outputs, power supplies)		
Connection charact (drive terminals for the li	eristics ine supply, the motor output a	nd the bra	aking unit)			
Drive terminals			R/L1, S/L2/N, T/L3, U/T1, V/T2, W/T3, PA/+,	PC/-		
Maximum wire size and tightening torque	ATV 12H018F1,H037F1 ATV 12H018M2H075M2 ATV 12H018M3H075M3 ATV 12P037F1 ATV 12P037M2P075M2 ATV 12P037M3,P075M3		3.5 mm ² (AWG 12) 0.8 Nm			
	ATV 12H075F1 ATV 12HU15M2,HU22M2 ATV 12HU15M3HU40M3 ATV 12PU15M3PU40M3		5.5 mm² (AWG 10) 1.2 Nm			

Electrical charac	teristics (control)		
Available internal supplies			Protected against short-circuits and overloads: One 5 V === supply (± 5%) for the reference potentiometer (2.2 to 10 k Ω) maximum data rate 10 mA One 24 V === supply (-15%/+20%) for the control inputs, maximum data rate 100 mA
Analog input	Al1		1 software-configurable voltage or current analog input: Voltage analog input: 05 V (internal power supply only) or 010 V , impedance 30 k Ω Analog current input: X-Y mA by programming X and Y from 020 mA, impedance 250 Ω Sampling time: < 10 ms Resolution: 10 bits Accuracy: ± 1% at 25°C Linearity: ± 0.3% of the maximum scale value Factory setting: Input configured as voltage type
Analog output	AO1		1 software-configurable voltage or current analog output: ■ Analog voltage output: 0 10 V === , minimum load impedance 470 Ω ■ Analog current output: 0 to 20 mA, maximum load impedance 800 Ω Update time: < 10 ms Resolution: 8 bits Accuracy: ± 1% at 25°C
Relay outputs	R1A, R1B, R1C		1 protected relay output, 1 N/O contact and 1 N/C contact with common point Response time: 30 ms maximum Minimum switching capacity: 5 mA for 24 V Maximum switching capacity: On resistive load (cos = 1 and L/R = 0 ms): 3 Aat 250 V ~ or 4 Aat 30 V On inductive load (cos = 0.4 and L/R = 7 ms): 2 Aat 250 V ~ or 30 V
LI logic inputs	LI1LI4		4 programmable logic inputs, compatible with PLC level 1, standard IEC/EN6 1131-2 24 V —— internal power supply or 24 V —— external power supply (min. 18 V, max. 30 V) Sampling time: < 20 ms Sampling time tolerance: ± 1 ms Factory-set with 2-wire control in "transition" mode for machine safety reasons: Ll1: forward Ll2:Ll4: not assigned Multiple assignment makes it possible to configure several functions on one input (for example: Ll1 assigned to forward and preset speed 2, Ll3 assigned to reverse and preset speed 3) Impedance 3.5 k Ω
	Positive logic (Source)		Factory setting State 0 if < 5 V, state 1 if > 11 V
	Negative logic (Sink)		Software-configurable State 0 if > 1 6 V or logic input not wired, state 1 if < 10 V
Logic output	LO+		One 24 V — logic output assignable as positive logic (Source) or negative logic (Sink) open collector type, compatible with level 1 PLC, standard IEC/EN 61131-2 Maximum voltage: 30 V Linearity: ± 1% Maximum current: 10 mA (100 mA with external power supply) Impedance: 1k \(\Omega\) Update time: < 20 ms Logic output common (LO-) to be connected to: 24 V — in positive logic (Source) 0 Vin negative logic (Sink)
Maximum I/O wire size and	tightening torque		1.5 mm² (AWG 14) 0.5 Nm
Acceleration and decelerat	cion ramps		Ramp profile: Linear from 0 to 999.9 s S ramp U ramp Automatic adaptation of deceleration ramp time if braking capacities exceeded, although this adaptation can be disabled (use of braking unit)
Emergency braking			By DC injection: automatically as soon as the estimated output frequency drops to < 0.2 Hz, period adjustable from 0.1 to 30 s or continuous, current adjustable from 0 to 1.2 ln
Main drive protection featu	ures		Thermal protection against overheating Protection against short-circuits between motor phases Overcurrent protection between motor phases and earth Protection in the event of line overvoltage and undervoltage Input phase loss protection, in three-phase
Motor protection			Thermal protection integrated in the drive by continuous calculation of the l^2t
Frequency resolution		•	Display unit: 0.1 Hz Analog inputs: 10-bit A/D converter
Time constant on a change	e of setpoint	ms	20±1 ms

DIMENSIONS:

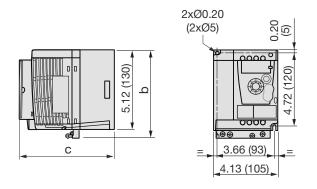
Dimensions are in inches (millimeters). Metric data is presented in (

ATV12H037F1M, ATV12H037M2M, ATV12H037M3M, ATV12H075M2M, ATV12H075M3M



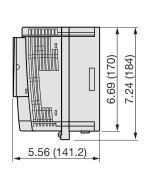
Advantage 12	b	С	Н
H037F1M, H037M2M, H037M3M	5.12	4.77	4.72
	(130)	(121.2)	(120)
H075M2M, H075M3M	5.12	5.17	4.72
	(130)	(13.21)	(120)

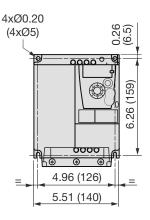
ATV12H075F1M, ATV12HU15M2M, ATV12HU22M2M, ATV12HU15M3M, ATV12HU22M3M



Advantage 12	b	С
H075F1M, HU15M2M, HU22M2M	5.12 (130)	6.15 (156.2)
HU15M3M, HU22M3M	5.12 (130)	5.17 (131.2)

ATV12HU40M3M





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